

Landau Damping

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1 Vlasov Equation for a Plasma

2 Landau Damping

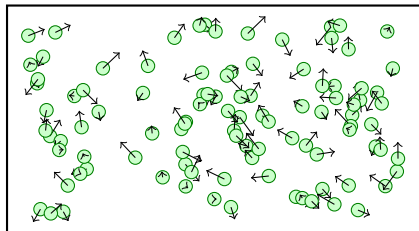
3 Time Reversibility

4 Outlook

What is a Plasma?

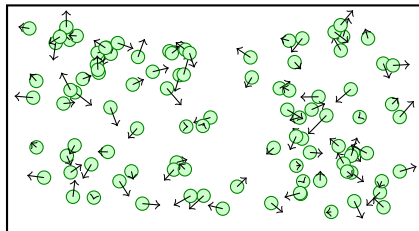
What is a Plasma?

A plasma is a gas with ionized particles (not necessarily all)

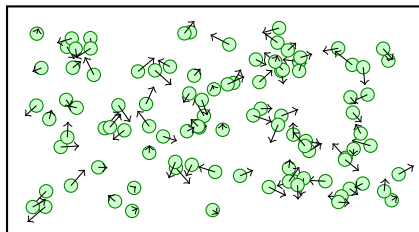


Here we consider freely moving electrons within a fixed background potential (ions are much heavier)

Level of Description

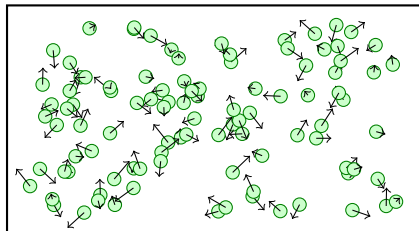


Level of Description



- Microscopic viewpoint
Use newtonian equations of motion for each particle

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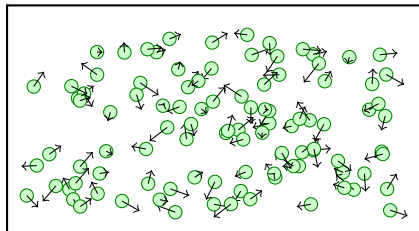


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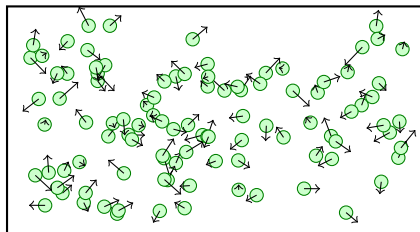
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 - Use newtonian equations of motion for each particle
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- Mesoscopic dynamics / Kinetic Theory
 - Look at distribution of particles

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- Mesoscopic dynamics / Kinetic Theory

Look at distribution of particles

- Ask how many particle are doing what
- Do not ask which particle

Equation of Motion

Physically the dynamic of a system is described by a Hamiltonian

$$H = \underbrace{\sum_{i=1}^n \frac{1}{2} \mathbf{v}_i^2}_{\text{kinetic energy}} + \underbrace{\sum_{i=1}^n \phi(\mathbf{x}_i)}_{\text{external potential}} + \underbrace{\sum_{i < j} \psi(\mathbf{x}_i - \mathbf{x}_j)}_{\text{Binary interaction}} \quad (1)$$

with equations of motion

$$\begin{aligned} \frac{d}{dt} \mathbf{x}_i &= \frac{\partial H}{\partial \mathbf{v}_i} = \mathbf{v}_i \\ \frac{d}{dt} \mathbf{v}_i &= -\frac{\partial H}{\partial \mathbf{x}_i} = -\nabla \phi(\mathbf{x}_i) - \sum_{i \neq j} \psi(\mathbf{x}_i - \mathbf{x}_j) \end{aligned} \quad (2)$$

Liouville Equation

Consider joint distribution function $F_N(t, \mathbf{x}_1, \mathbf{v}_1, \dots, \mathbf{x}_n, \mathbf{v}_n)$. Claim evolution by

$$\frac{\partial F_N}{\partial t} + \sum_{i=1}^n \left(\frac{\partial H}{\partial \mathbf{v}_i} \cdot \frac{\partial F_N}{\partial \mathbf{x}_i} - \frac{\partial H}{\partial \mathbf{x}_i} \cdot \frac{\partial F_N}{\partial \mathbf{v}_i} \right) = 0 \quad (3)$$

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- Expected if considering Poisson brackets
- Constant along trajectories
- Reduces to equation of motion for point masses
- Same amount of information

One Particle Distribution

Try to describe the system by marginal distribution

$$f^{(1)}(t, \mathbf{x}, \mathbf{v}) = \int F_N(t, \mathbf{x}, \mathbf{v}, \mathbf{x}_2, \mathbf{v}_2, \dots, \mathbf{x}_n, \mathbf{v}_n) d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n \quad (4)$$

and assume symmetry.

Find dynamic equation by integrating Liouville equation

$$\frac{\partial F_N}{\partial t} + \sum_{i=1}^n \left(\frac{\partial H}{\partial \mathbf{v}_i} \cdot \frac{\partial F_N}{\partial \mathbf{x}_i} - \frac{\partial H}{\partial \mathbf{x}_i} \cdot \frac{\partial F_N}{\partial \mathbf{v}_i} \right) = 0 \quad (5)$$

Dynamic Equation for $f^{(1)}$

Recall

$$\frac{\partial F_N}{\partial t} + \sum_{i=1}^n \left(\frac{\partial H}{\partial \mathbf{v}_i} \cdot \frac{\partial F_N}{\partial \mathbf{x}_i} - \frac{\partial H}{\partial \mathbf{x}_i} \cdot \frac{\partial F_N}{\partial \mathbf{v}_i} \right) = 0$$
$$H = \sum_{i=1}^n \frac{1}{2} \mathbf{v}_i^2 + \sum_{i=1}^n \phi(\mathbf{x}_i) + \sum_{i < j} \psi(\mathbf{x}_i - \mathbf{x}_j)$$

Integrate first term

$$\int \frac{\partial F_N}{\partial t}(t, \mathbf{x}_1, \mathbf{v}_1, \mathbf{x}_2, \mathbf{v}_2, \dots, \mathbf{x}_n, \mathbf{v}_n) d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n = \frac{\partial f^{(1)}}{\partial t}(t, \mathbf{x}_1, \mathbf{v}_1)$$

Dynamic Equation for $f^{(1)}$

Recall

$$\frac{\partial F_N}{\partial t} + \sum_{i=1}^n \left(\frac{\partial H}{\partial \mathbf{v}_i} \cdot \frac{\partial F_N}{\partial \mathbf{x}_i} - \frac{\partial H}{\partial \mathbf{x}_i} \cdot \frac{\partial F_N}{\partial \mathbf{v}_i} \right) = 0$$
$$H = \sum_{i=1}^n \frac{1}{2} \mathbf{v}_i^2 + \sum_{i=1}^n \phi(\mathbf{x}_i) + \sum_{i < j} \psi(\mathbf{x}_i - \mathbf{x}_j)$$

Integrate second term

$$\int \sum_{i=1}^n \left(\frac{\partial H}{\partial \mathbf{v}_i} \cdot \frac{\partial F_N}{\partial \mathbf{x}_i} \right) d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n = \int \frac{\partial H}{\partial \mathbf{v}_1} \cdot \frac{\partial F_N}{\partial \mathbf{x}_1} d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n$$
$$= \mathbf{v}_1 \cdot \frac{\partial f^{(1)}}{\partial \mathbf{x}_1}$$

Dynamic Equation for $f^{(1)}$

Recall

$$\frac{\partial F_N}{\partial t} + \sum_{i=1}^n \left(\frac{\partial H}{\partial \mathbf{v}_i} \cdot \frac{\partial F_N}{\partial \mathbf{x}_i} - \frac{\partial H}{\partial \mathbf{x}_i} \cdot \frac{\partial F_N}{\partial \mathbf{v}_i} \right) = 0$$
$$H = \sum_{i=1}^n \frac{1}{2} \mathbf{v}_i^2 + \sum_{i=1}^n \phi(\mathbf{x}_i) + \sum_{i < j} \psi(\mathbf{x}_i - \mathbf{x}_j)$$

Integrate third term

$$\int \sum_{i=1}^n \left(\frac{\partial H}{\partial \mathbf{x}_i} \cdot \frac{\partial F_N}{\partial \mathbf{v}_i} \right) d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n = \int - \frac{\partial H}{\partial \mathbf{x}_1} \cdot \frac{\partial F_N}{\partial \mathbf{x}_1} d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n$$
$$= - \int \left(\frac{\partial \phi}{\partial \mathbf{x}_1} + \sum_{j=2}^n \frac{\partial \psi}{\partial \mathbf{x}_1}(\mathbf{x}_1 - \mathbf{x}_j) \right) \cdot \frac{\partial F_N}{\partial \mathbf{x}_1} d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n$$

Dynamic Equation for $f^{(1)}$

Integrate third term

$$\begin{aligned} \int \sum_{i=1}^n \left(\frac{\partial H}{\partial \mathbf{x}_i} \cdot \frac{\partial F_N}{\partial \mathbf{v}_i} \right) d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n &= \int -\frac{\partial H}{\partial \mathbf{x}_1} \cdot \frac{\partial F_N}{\partial \mathbf{x}_1} d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n \\ &= - \int \left(\frac{\partial \phi}{\partial \mathbf{x}_1} + \sum_{j=2}^n \frac{\partial \psi}{\partial \mathbf{x}_1} (\mathbf{x}_1 - \mathbf{x}_j) \right) \cdot \frac{\partial F_N}{\partial \mathbf{x}_1} d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n \\ &= -\frac{\partial \phi}{\partial \mathbf{x}_1}(\mathbf{x}_1) \cdot \frac{\partial f^{(1)}}{\partial \mathbf{v}_1} - (n-1) \int \frac{\partial \psi}{\partial \mathbf{x}_1}(\mathbf{x} - \mathbf{x}_2) \cdot \frac{\partial F_N}{\partial \mathbf{x}_1} d\mathbf{x}_2 d\mathbf{v}_2 \dots d\mathbf{x}_n d\mathbf{v}_n \\ &= -\frac{\partial \phi}{\partial \mathbf{x}_1}(\mathbf{x}_1) \cdot \frac{\partial f^{(1)}}{\partial \mathbf{v}_1} - (n-1) \int \frac{\partial \psi}{\partial \mathbf{x}_1}(\mathbf{x} - \mathbf{x}_2) \cdot \frac{\partial f^{(2)}}{\partial \mathbf{x}_1} d\mathbf{x}_2 d\mathbf{v}_2 \end{aligned}$$

where

$$f^{(2)}(t, \mathbf{x}_1, \mathbf{v}_1, \mathbf{x}_2, \mathbf{x}_2) = \int F_N(t, \mathbf{x}_1, \mathbf{v}_1, \mathbf{x}_2, \mathbf{v}_2, \dots, \mathbf{x}_n, \mathbf{v}_n) d\mathbf{x}_3 d\mathbf{v}_3 \dots d\mathbf{x}_n d\mathbf{v}_n$$

Dynamic Equation for $f^{(1)}$

Putting everything together gives

$$\begin{aligned} \frac{\partial f^{(1)}}{\partial t}(t, \mathbf{x}, \mathbf{v}) + \mathbf{v} \cdot \frac{\partial f^{(1)}}{\partial \mathbf{x}}(t, \mathbf{x}, \mathbf{v}) - \frac{\partial \phi}{\partial \mathbf{x}}(\mathbf{x}) \cdot \frac{\partial f^{(1)}}{\partial \mathbf{v}}(t, \mathbf{x}, \mathbf{v}) \\ - (n-1) \int \frac{\partial \psi}{\partial \mathbf{x}}(\mathbf{x} - \mathbf{y}) \frac{\partial f^{(2)}}{\partial \mathbf{v}}(t, \mathbf{x}, \mathbf{v}, \mathbf{y}, \mathbf{u}) d\mathbf{y} d\mathbf{u} = 0 \end{aligned} \quad (6)$$

- BBGKY hierarchy
- Need to break chain down
- Use Molecular Chaos (Boltzmann) as $n \rightarrow \infty$

$$f^{(2)} = f^{(1)} \otimes f^{(1)} \quad (7)$$

- Need appropriate scaling as $n \rightarrow \infty$

Mean Field Approximation

Ignore collisions and assume particle only influenced by mean field

$$(n-1) \int \frac{\partial \psi}{\partial \mathbf{x}}(\mathbf{x} - \mathbf{y}) \frac{\partial f^{(2)}}{\partial \mathbf{v}}(t, \mathbf{x}, \mathbf{v}, \mathbf{y}, \mathbf{u}) d\mathbf{y} d\mathbf{u} \approx - \frac{\partial V}{\partial \mathbf{x}}(\mathbf{x}) \frac{\partial f^{(1)}}{\partial \mathbf{v}} \quad (8)$$
$$V = - \int \psi(\mathbf{x} - \mathbf{y}) f^{(1)}(\mathbf{y}, \mathbf{v}) d\mathbf{y} d\mathbf{v}$$

With Coulomb interaction $\psi(\mathbf{x} - \mathbf{y}) \propto \frac{1}{|\mathbf{x} - \mathbf{y}|}$ and recalling fundamental solution to Poisson equation

$$\nabla^2 V(t, \mathbf{x}) = \int f^{(1)}(t, \mathbf{x}, \mathbf{v}) d\mathbf{v} \quad (9)$$

Vlasov Equation

Including the background potential we arrived at **Vlasov equation**

$$\begin{aligned}\frac{\partial f}{\partial t} + \mathbf{v} \frac{\partial f}{\partial \mathbf{x}} - \nabla V \cdot \frac{\partial f}{\partial \mathbf{v}} &= 0 \\ \nabla^2 V &= \rho_{ions} - \int f d\mathbf{v}\end{aligned}\tag{10}$$

Assume overall neutrality, i.e.

$$\int \rho_{ions} d\mathbf{x} = \int f d\mathbf{x} d\mathbf{v}\tag{11}$$

Maxwell Distribution

The equilibrium distribution at temperature T is the *Maxwell distribution* f_0

$$f_0(\mathbf{v}) \propto e^{-\mathbf{v}^2/2T} \quad (12)$$

- Follows from Boltzmann distribution / canonical ensemble
- Maxwell's original argument uses proposed symmetry
- Boltzmann H-Theorem explains why with collisions the system relaxes towards the Maxwell distribution

Linearised Equation around Maxwell Distribution

We want to consider a small perturbation h around equilibrium

$$f(t, \mathbf{x}, \mathbf{v}) = f_0(\mathbf{v}) + h(t, \mathbf{x}, \mathbf{v}) \quad (13)$$

Vlasov equation

$$\begin{aligned} \frac{\partial f}{\partial t} + \mathbf{v} \frac{\partial f}{\partial \mathbf{x}} - \nabla V \cdot \frac{\partial f}{\partial \mathbf{v}} &= 0 \\ \nabla^2 V &= \rho_{ions} - \int f d\mathbf{v} \end{aligned} \quad (14)$$

Linearised Vlasov equation

$$\begin{aligned} \frac{\partial h}{\partial t} + \mathbf{v} \frac{\partial h}{\partial \mathbf{x}} - \nabla V \cdot \frac{\partial f_0}{\partial \mathbf{v}} &= 0 \\ \nabla^2 V &= - \int h d\mathbf{v} \end{aligned} \quad (15)$$

Assuming contribution from ions cancels with contribution from f_0 .

Split into Fourier Modes

Linearised Vlasov equation

$$\frac{\partial h}{\partial t} + \mathbf{v} \frac{\partial h}{\partial \mathbf{x}} - \nabla V \cdot \frac{\partial f_0}{\partial \mathbf{v}} = 0$$
$$\nabla^2 V = - \int h \, d\mathbf{v}$$

These equations are linear, so consider Fourier modes separately. Consider:

$$h_{\mathbf{k}}(\mathbf{v}, t) e^{i(\mathbf{k}\mathbf{x})}$$

Mode equation

Dropping index \mathbf{k} , and assume k along x -axis:

$$\frac{\partial h}{\partial t} + ikv_x h - ikV \frac{\partial f_0}{\partial v_x} = 0$$
$$k^2 V = \int h \, d\mathbf{v}$$

Solving using Laplace Transformation

Introduce Laplace transformation in time

$$h_p(\mathbf{v}) = \int_0^{\infty} h(\mathbf{v}, t) e^{-pt} dt \quad (16)$$

then ($\sigma > 0$):

$$h(t, \mathbf{v}) = \int_{-i\infty+\sigma}^{i\infty+\sigma} h_p(\mathbf{v}) e^{pt} dp \quad (17)$$

Solution in Laplace Transformation

Using integration by parts and simple algebra we find with initial condition $g(\mathbf{v}) = h(t, \mathbf{v})$:

$$h_p(\mathbf{v}) = \frac{1}{p + ikv_x} \left(g(\mathbf{v}) + ikV_p \frac{\partial f_0(\mathbf{v})}{\partial v_x} \right)$$

$$V_p = \frac{1}{k^2} \cdot \frac{\int \frac{g(\mathbf{v})}{p + ikv_x} d\mathbf{v}}{1 - \frac{i}{k^2} \int \frac{\partial f_0}{\partial v_x} \frac{d\mathbf{v}}{(p + ikv_x)}}$$

Simplify Solution

Integrate out trivial directions dv_y, dv_z

$$g(u) = \int g(\mathbf{v}) dv_y dv_z \quad (18)$$

Find

$$V_p = \frac{1}{k^2} \cdot \frac{\int_{-\infty}^{\infty} \frac{g(u)}{p+iku} du}{1 - \frac{i}{k^2} \int_{-\infty}^{\infty} \frac{df_0}{du} \frac{du}{(p+iku)}}$$

$$f_0(u) = n \sqrt{\frac{1}{2\pi T}} e^{-\frac{u^2}{2T}}$$

Investigate Solution

Laplace transformation

$$h_p = \int_0^{\infty} h(t)e^{-pt} dt$$

only defined for p in the right half plane. Extend through analytic continuation.

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has poles p_k at

$$\frac{i}{k^2} \int \frac{df_0}{du} \frac{du}{(p+iku)} = 1 \quad (19)$$

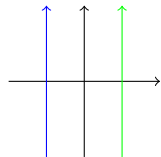
As $\frac{df_0}{du} > 0$, all poles are in the left half plane.

Asymptotic Solution

Recall inversion formula ($\sigma > 0$)

$$h(t) = \frac{1}{2\pi i} \int_{-i\infty+\sigma}^{\sigma} h_p e^{pt} dp$$

Shift contour into the left half plane

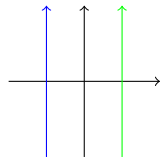


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For $t \rightarrow \infty$ only contributions from poles:

- poles are in the left half plane
- decaying potential V

Limiting behaviour

So we can summarise the limiting behaviour as $t \rightarrow \infty$

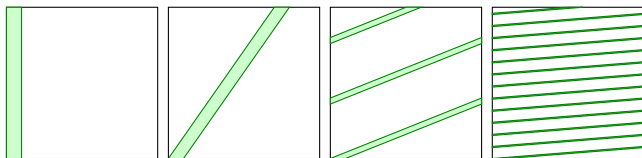
- Potential V is decaying
- Perturbation h is **not** decaying

Time Reversibility

Vlasov equation is time-reversible, so if there are decaying modes there should also be growing modes

- Linearised Equation is not time-reversible
- How does the non-linear term evolve?

Phase Mixing



- Strong vs. Weak topology
Only the potential V is decaying. The perturbation h is oscillating.

Outlook

- For what equilibrium distribution does the linear damping occur?

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Penrose Criterion

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- For what equilibrium distribution does the linear damping occur?
Penrose Criterion
- Recently Mouhot and Villani gave a theorem for non-linearised theory

Acknowledgement

I would like to thank Dr Mouhot for introducing me to this area.